

State Space Search in AI

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Introduction

The search space is generally represented as a directed graph (in fact a tree), with vertices as states, and edges of the graph as transitions for moves to explore for the goal state.

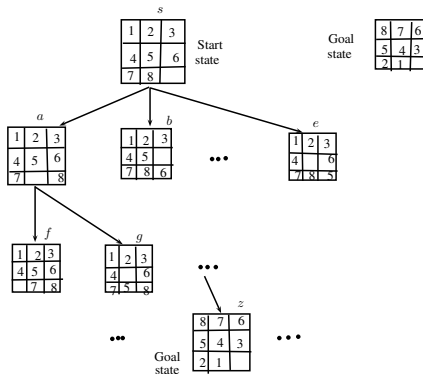


Figure 1: The 8-puzzle Game.

Evaluation of Search Strategies

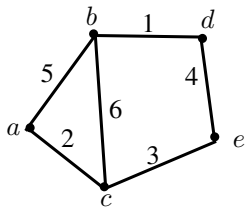
The Search Strategies are evaluated along the following dimensions:

- *Completeness*: Does it always find a solution if one exists?
- *Time complexity*: What is to be Number of nodes generated ?
The duplicate nodes generated due to multiple paths, are also counted.
- *Space complexity*: What is maximum number of nodes in memory at any time?
- *Optimality*: Does it always find a least-cost solution?

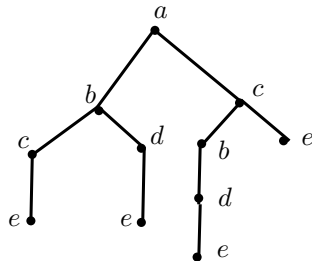
AI search is graph search

Example

Consider the graph shown in figure 2 for a small size problem, where it is required to reach to goal state g from the start state a .



Start node = a
Goal node = e



(a) Graph with states a - e .

(b) Graph search is a tree.

Figure 2: Undirected graph.

Uninformed Search

- It is also called blind search, because we do not know, which direction move(s) ultimately will lead to goal faster.
- Since all the nodes are required to be searched - the search is called *exhaustive* search.
- To search the entire state space, the two important approaches are - *breadth-first search* (BFS) or *depth-first search* (DFS).

Breadth-First Search

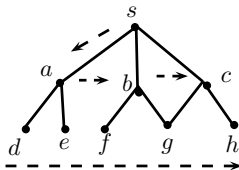


Figure 3: Breadth-first Search.

The *BFS* can be implemented using a *queue* type data structure, named here as **List**. The front node of the of the queue is represented by **List.Head**.

Breadth-First Search Algorithm

Algorithm 1 BFS(Input: **G**, **S**, **Goal**)

```
1: List = [S]  
2: repeat  
3:   if List.Head = Goal then  
4:     return success  
5:   end if  
6:   generate children set C of List.Head  
7:   append C to List  
8:   delete List.Head  
9: until List = []  
10: return fail
```

Depth-First Search

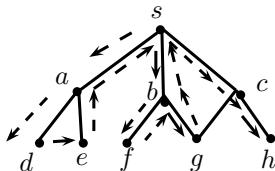


Figure 4: Depth-first Search.

To perform a DFS search, we generate all the next states for the root node, then pickup the left-most node, generate the children for this, check for goal, and repeat this, until we reach to goal or the dead end.

Depth-First Search Algorithm

Algorithm 2 DFS(Input: **G**, **S**, **Goal**)

```
1: List = [S]  
2: repeat  
3:   if List.Head = Goal then  
4:     return success  
5:   end if  
6:   generate children set C of List.Head  
7:   delete List.Head  
8:   insert C at begin of List  
9: until List = []  
10: return fail
```

- **BFS:**

- Let us assume that in the tree constructed in a search has depth d and for each node there are b nodes that gets generated, called *branching factor*
- For a *BFS* search, total nodes visited for tree of depth d are:

$$1 + b + b^2 + \dots + b^n = O(b^d), \quad (1)$$

- The maximum number of nodes in the 'Open-list' will be at the lowest level of the tree. Thus space-complexity is $O(b^d)$.

- **DFS:**
- For a *DFS* search, in the worst-case all the nodes are visited. Hence, time-complexity is same as for *BFS*, and equal to $O(b^d)$.
- Since, *DFS* needs to store only b nodes per level for a depth of d , the total nodes to be stored are $b \times d$, and space-complexity is $O(bd)$.

Depth-First Iterative Deepening (DFID) Search

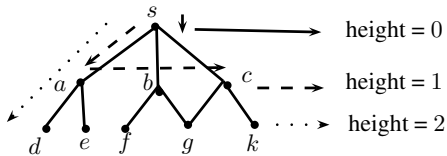


Figure 5: Search tree of Iterative deepening DFS.

Bidirectional Search

- If the search is carried out in both the directions, it can be speeded up.
- Consider that a bidirectional search is carried out with the depth as d and branching factor b .
- If each side progresses with same depth, the search required from each, for example, for iterative deepening *DFS*, has $O(b^{\frac{d}{2}})$ for time, and $O(b^{\frac{d}{2}})$ for space.
- When combined from both opposite sides, it becomes $2 \times O(b^{\frac{d}{2}}) = O(b^{\frac{d}{2}})$ for *time*, and $2 \times O(b \times \frac{d}{2}) = O(bd)$ for *space*.

Problem formulation for Search

Example

Farmer, goose, grains, fox problem.

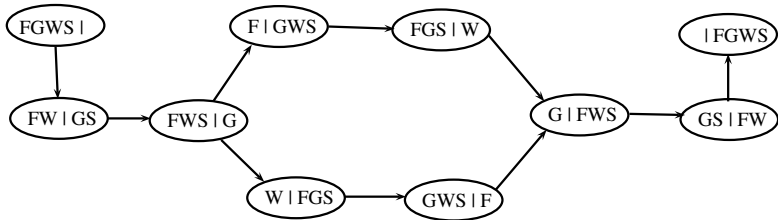


Figure 6: Farmer-goose-grains-fox Problem as Graph search.

How much you have understood?

- 1 The BFS uses what data structure?
- 2 The DFS uses what data structure?
- 3 Time complexity of DFS is
- 4 Time complexity of BFS is
- 5 Space complexity of DFS is ...
- 6 Space complexity is
- 7 Assuming that there are 100 moves in a game of chess, and there are 20 possible alternatives per move, what is total possible number of chess games?
- 8 The answer of above concludes what?