

Operating system concepts

Types of OS

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Recommended Reading

- ▶ *Operating System concepts*, by Abraham Silerschatz, Peter Baer Galvin, and Greg Gagne (Important: Available online, pdf free downloadable)
- ▶ *Operating Systems*, by Stuart Madnick, John Donovan, McGraw Hill Education, 2017
- ▶ *Operating System Concepts and Design*, Milan Milenkovic, Mcgraw-Hill.

Types of operating systems

1. Batch processing operating systems
2. Multiprogramming operating systems
3. Time sharing operating systems
4. Real-time operating system
5. Distributed operating System
6. Combination operating systems

Punch card machine



Figure 1: A punch card

Batch System

- ▶ Use of tape drives allow batching of jobs:
 - ▶ programmers put jobs on cards as before.
 - ▶ all cards read onto a tape.
 - ▶ operator carries input tape to computer.
 - ▶ results written to output tape.
 - ▶ output tape taken to printer.
- ▶ Computer now has a resident monitor :
 - ▶ initially control is in monitor.
 - ▶ monitor reads job and transfer control.
 - ▶ at end of job, control transfers back to monitor.
- ▶ Even better: spooling systems.
 - ▶ use interrupt driven I/O.
 - ▶ use magnetic disk to cache input tape.
 - ▶ file operation.
- ▶ Monitor now schedules jobs. . .

Multi-programming

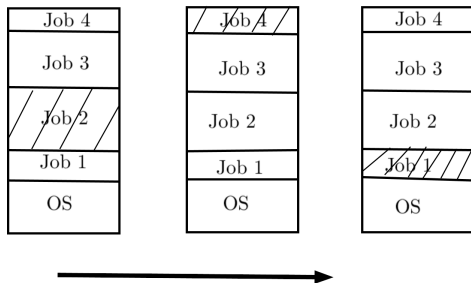


Figure 2: Multi-programming

Multi-programming....

- ▶ Use memory to cache jobs from disk \Rightarrow more than one job active simultaneously.
- ▶ Two stage scheduling:
 1. select jobs to load: job scheduling.
 2. select resident job to run: CPU scheduling.
- ▶ Users want more interaction \Rightarrow time-sharing:
- ▶ e.g. CTSS (compatible time-sharing system), TSO (time sharing options), Unix, VMS, Windows NT. . .
- ▶ DOS?

Real-time Operating Systems (RTOS)

Time interval required to process and respond to inputs is small

- ▶ Small *response time*
- ▶ They used when there are rigid time requirements
- ▶ Examples: Scientific experiments, medical imaging systems, industrial control systems, weapon systems, robots, air traffic control systems, etc.
- ▶ Types of RTOS:
 - ▶ Hard real-time systems
 - ▶ Soft real-time systems : multimedia, virtual reality, Advanced Scientific Projects like undersea exploration and planetary rovers, etc

Multi-process Operating Systems

- ▶ These are used to boost the performance that uses multiple processes in a single computer system.
- ▶ Multiple CPUs are linked together so that a job can be divided and executed more quickly.
- ▶ There may or may not be multiple CPUs
- ▶ Programs run as processes in round-robin fashion, like a grand master chess player plays with many learner chess players playing on different chess boards.

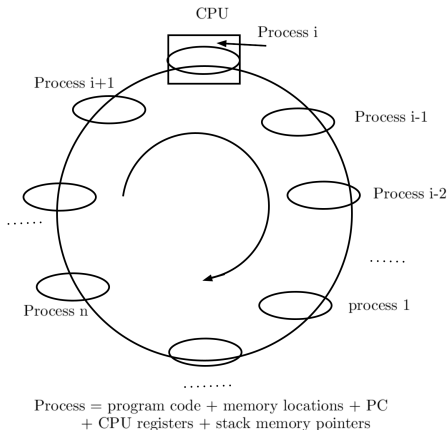


Figure 3: Multi-processing OS

Time-sharing OS

An operating system design that allows multiple users or processes to concurrently share the same system resources, such as the CPU, memory, and peripherals.

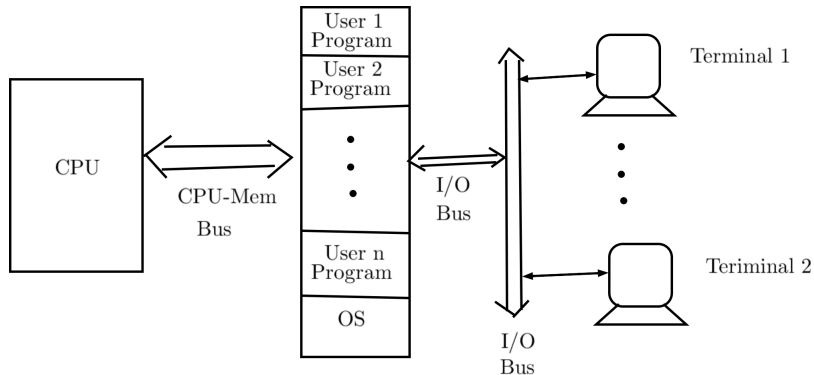


Figure 4: Time sharing operating system

Distributed OS

- ▶ A distributed operating system is one that looks to its users like an ordinary centralized operating system but runs on multiple, independent central processing units (CPUs).
- ▶ The key concept here is transparency. In other words, the use of multiple processors should be invisible (transparent) to the user.
- ▶ *Distributed Applications*: LinkedIn, FB, InstaGram, X, Google search. *Distributed OS*: Solaris, Ubuntu, Linux, OSF/1, Dynix, Locus
- ▶ *Terms*: Distributed Algorithms, distributed systems, distributed applications, distributed computing, distributed databases, distributed file systems, distributed ledger technology (block chain).
- ▶ A fundamental problem in distributed systems: Lack of global state information.

Monolithic Operating Systems

- ▶ Oldest kind of OS structure (are DOS, original MacOS)
- ▶ Problems:
 - ▶ Single process OS software
 - ▶ One application runs at a time
 - ▶ dedicated CPU
 - ▶ misuse I/O devices
 - ▶ etc. . .
- ▶ No good for fault containment (or multi-user).
- ▶ Need a better solution ?

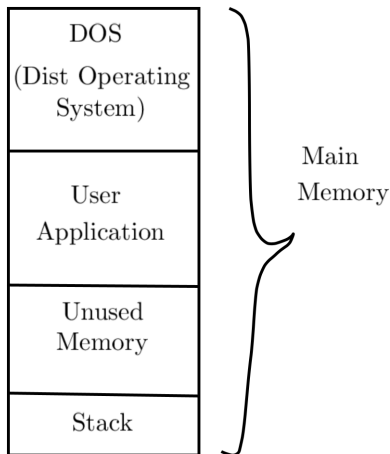


Figure 5: Monolithic os

Dual-Mode Operation (Why it is needed?)

- ▶ Stops buggy (or malicious) program from doing bad things
- ▶ provide hardware support to distinguish between two different modes of operation:
 - ▶ *User Mode* : executing on behalf of a user (i.e., application programs)
 - ▶ *Kernel Mode* : executing on behalf of the operating system

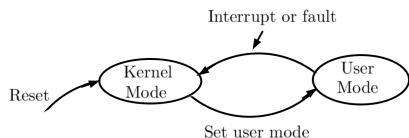


Figure 6: User and kernel mode

- ▶ Interrupt, e.g., pressing a key by user, fault, e.g., page-fault, i.e., required data is not found in RAM, so it should be brought from disk
- ▶ Mode bit in hardware, e.g. 0 = kernel, 1 = user mode
- ▶ Some machine instructions are possible in kernel mode only